



Eisenhart lift of Koopman-von Neumann mechanics

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ABSTRACT

The Eisenhart lift establishes a fascinating connection between non-relativistic and relativistic physics, providing a space-time geometric understanding of non-relativistic Newtonian mechanics. What is still little known, however, is the fact that there is a Hilbert space representation of classical mechanics (also called Koopman-von Neumann mechanics) that attempts to give classical mechanics the same mathematical structure that quantum mechanics has. In this article, we geometrize the Koopman-von Neumann (KvN) mechanics using the Eisenhart toolkit. We then use a geometric view of KvN mechanics to find transformations that relate the harmonic oscillator, linear potential, and free particle in the context of KvN mechanics.

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1. Introduction

Attempts to understand physical interactions in terms of geometry began shortly after Einstein's theory of general relativity in 1915 (although, in fact, attempts to understand mechanics geometrically have a much richer history, see, for example, [63]). In 1928, Eisenhart proposed a variant of the geometrization of the Newtonian equations of motion of classical mechanics with d degrees of freedom in terms of geodesics of a $(d + 2)$ -dimensional Lorentzian manifold with a Brinkmann-type metric. This formalism is called the Eisenhart lift, where the word lift indicates the necessity to introduce extra dimensions to achieve proper geometrization. However, surprisingly, Eisenhart's original publication [37] did not attract much attention and had fallen into oblivion until the idea was rediscovered in the modern coordinate-independent approach (the so-called Bargmann structure approach) by Duval in 1985 [32,33,70]. This time these new advances have attracted attention and led to further progress in this direction, see [15,23,24,30,40,55,96] and references therein for some modern applications, including an important relation between the relativistic field equation and the Schrödinger equation [23,32].

Newtonian mechanics provides us with the mathematical toolkit to understand the classical world. However, the advent of quantum mechanics required a unique mathematical formalism associated with it, different from the mathematical structure used in classical physics. The change in the mathematical structure during the transition from the microscopic world (the quantum world) to the macroscopic world (the classical world) is still a mystery. Koopman-von-Neumann (KvN) mechanics arose as a result of attempts to formulate both classical and quantum mathematical formalism on the same basis

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of Hilbert spaces. The search for such a unified mathematical basis for both quantum and classical mechanics is still the subject of ongoing research, and two different points of view prevail in the scientific community. While some authors prefer to have a symplectic view of quantum mechanics [6,7,10,50,64,65,75], others tend to move in the direction indicated by Koopman and von Neumann [60,90] of establishing a Hilbert space representation of classical mechanics [2,25,46,47,66,67].

The Eisenhart lift of Newtonian mechanics is well known and studied. However, in this article we will develop the Eisenhart lift of the Koopman-von Neumann mechanics and point out some applications of the introduced formalism.

2. Emergence of classicality from quantum world

2.1. Emergence of classical mechanics I

Initially, classical mechanics, in the non-relativistic realm, was usually understood in the Newtonian sense. However, over time, classical mechanics has evolved from Newtonian formalism to mathematically more complex Lagrangian and Hamiltonian formulations that have given us a deep understanding of the symmetry, mathematical structures, etc. of classical dynamical systems. The Hamiltonian formalism, in particular, played a significant role in the construction of quantum mechanics and the corresponding mathematical apparatus in a Hilbert space. Both classical and quantum theories find their application in explaining the macroscopic and microscopic worlds, respectively. However, the emergence of the classical macroscopic world from the underlying microscopic quantum world is not so straightforward to understand. In particular, the emergence of classicality from quantum mechanics is still a subject of debate [45]. We would not be completely satisfied with either a naively attractive way of obtaining classicality from quantum theory using the $\hbar \rightarrow 0$ limit [74], nor reasoning based on the Ehrenfest theorem [79], nor any approximate methods or arguments proposed by decoherence experts [11,77]. This is due to the fact that all of them are fraught with some conceptual problems and/or problems of mathematical rigor, see, for example, [16,17,52,58].

Nevertheless, ignoring possible mathematical and conceptual subtleties, let us briefly outline the use of the $\hbar \rightarrow 0$ limit to derive classicality from a quantum theory. It might be expected that after such a limiting procedure we would obtain Newton's equation directly from the Schrödinger equation, which, however, is not the case and we actually arrive at the Hamilton-Jacobi (HJ) equation [58]. The procedure for obtaining the HJ equation includes the Madelung substitution $\psi = \sqrt{\rho} e^{iS/\hbar}$ in the Schrödinger equation and the separation of the real and imaginary parts of the resulting equation. Then, in the limit $\hbar \rightarrow 0$, we get a system whose second equation is formally identical to the Hamilton-Jacobi equation (Einstein summation convention is used):

$$\begin{aligned} \frac{\partial \rho}{\partial t} + \frac{\partial}{\partial x_i} (\rho v_i) &= 0, \quad v_i = \frac{1}{m} \frac{\partial S}{\partial x_i}, \\ \frac{\partial S}{\partial t} + \frac{1}{2m} \left(\frac{\partial S}{\partial x_i} \right)^2 + V(x, t) &= 0. \end{aligned} \tag{1}$$

However, the system (1) still describes the probabilistic situation of the statistical ensemble, as evidenced by the presence of the first equation, and not a Newtonian particle moving along a certain trajectory. Indeed, it can be shown [78,89] that if we start with the Liouville equation in phase space

$$\begin{aligned} \frac{\partial f(\vec{x}, \vec{p}, t)}{\partial t} &= \{H(\vec{x}, \vec{p}, t), f(\vec{x}, \vec{p}, t)\}, \\ \{H, f\} &= \frac{\partial H}{\partial x_i} \frac{\partial f}{\partial p_i} - \frac{\partial H}{\partial p_i} \frac{\partial f}{\partial x_i}, \end{aligned} \tag{2}$$

and make the hydrodynamic substitution $f(\vec{x}, \vec{p}, t) = \rho(\vec{x}, t) \delta(\vec{p} - m\vec{v}(\vec{x}, t))$, one can obtain equations equivalent to the system (1) from (2).

To obtain a deterministic limit of (1) and hence of Schrödinger equation, we must assume that $\rho(\vec{x}, t)$ takes the form of a delta function peaked at the Newtonian trajectory. More precisely, the procedure is as follows [58]. First it can be shown that the ansatz

$$\rho(\vec{x}, t) = \left(\frac{1}{\pi \epsilon} \right)^{3/2} \exp \left\{ -\frac{1}{\epsilon} (\vec{x} - \vec{r}(t))^2 \right\}, \tag{3}$$

which represents $\delta(\vec{x} - \vec{r}(t))$ in the limit $\epsilon \rightarrow 0$, is under this limit a valid solution of the first continuity equation of (1) for arbitrary S . Then Hamilton equations are obtained for averaged ρ values $\bar{x}_k(t) = \int d\vec{x} \rho(\vec{x}, t) x_k$ and $\bar{p}_k(t) = \int d\vec{x} \rho(\vec{x}, t) \frac{\partial S(\vec{x}, t)}{\partial x_k}$. Finally, it is shown that in the limit $\epsilon \rightarrow 0$ we have $\bar{x}_k(t) = r_k(t)$, $\bar{p}_k(t) = m\dot{r}_k(t)$, and, so it follows from the Hamilton equations that $r_k(t)$ is a Newtonian trajectory.

2.2. Emergence of classical mechanics II

There is a subtlety in the derivation of the classical limit, evident from the previous discussion: classicality does not arise simply as the limit $\hbar \rightarrow 0$ (or the limit $m \rightarrow \infty$, where m is the mass of the particle) of the Schrödinger equation. This

subtlety was noted already by Einstein in his essay on the occasion of Born's retirement from his Chair at the University of Edinburgh in 1952 [12]. Einstein considered a free particle in an energy eigenstate moving between two reflecting walls and remarked that in the classical limit $m \rightarrow \infty$ (but with the energy fixed) the quantum mechanical description does not go over into the classical description of a body with a well-defined center of mass that oscillates between the walls. Rather, in this limit, the wave function describes the behavior of an ensemble of identical bodies in the sense of classical statistical mechanics. In his answer, Born pointed out, in line with point of view [58] outlined above, that one should take a sharply localized wave packet rather than an energy eigenstate before passing to the macroscopic limit [12]. However, Einstein insisted that the quantum wave function must be considered to describe an ensemble of similar systems, and cannot be considered as a complete description of an individual system, as advocated by Bohr and subsequently accepted in the canonical Copenhagen interpretation of quantum mechanics [12,36]. From Einstein's point of view, in a proper quantum ontology, the classical description must be restored in the macroscopic limit for all solutions of the Schrödinger equation, not just for a limited class, and he emphasized that this requires the adoption of an ensemble interpretation in which there are no difficulties regarding the classical limit [12]. An interesting counterexample to Einstein's claim that the classical description must always be restored in the macroscopic limit is provided by the cryogenic version of the Weber bar (a gravitational wave detector), which must be treated quantum mechanically even though it may weigh over a ton [97].

In fact, it is quite natural to expect that the probabilistic picture inherent in quantum mechanics in the classical limit corresponds to a similar probabilistic picture in the phase space, as indicated by the Liouville equation. It can be easily checked that, since the Liouville equation is linear in derivatives, the square root of the phase space probability density $\psi(\vec{x}, \vec{p}, t) = \sqrt{f(\vec{x}, \vec{p}, t)}$ obeys the same Liouville equation (2). If we assume that $\psi(\vec{x}, \vec{p}, t)$ is complex, then it can be viewed as a kind of wave function (in phase space) attributed to a classical particle (or system), and the Liouville equation can be rewritten in the Schrödinger-like form

$$i\hbar \frac{\partial \psi(q, p, t)}{\partial t} = \hat{L} \psi(q, p, t) \tag{4}$$

where \hat{L} is the Liouville operator given by

$$\hat{L} = i\hbar \{H, \} = i\hbar \left(\frac{\partial H}{\partial q} \frac{\partial}{\partial p} - \frac{\partial H}{\partial p} \frac{\partial}{\partial q} \right). \tag{5}$$

Using this fact a quantum-like Hilbert space formalism, pioneered by Koopman and von Neumann [60,90], can be developed for classical statistical mechanics. The fundamental difference between the quantum and classical cases is that [59] in the latter case, if we make the Madelung substitution for the classical wave function, we get decoupled differential equations for $\sqrt{\rho}$ and S , in contrast to the quantum case.

Using the fact that in the classical limit there is a mapping between the Wigner quasi-probability distribution function and the KvN wave function [19], it can be shown that the KvN equation naturally arises from the quantum picture in the classical limit, if we start from the representation of quantum mechanics in the phase space instead of configuration space.

The Wigner function is given by (for simplicity, one-dimensional systems are considered throughout)

$$W(q, p) = \frac{1}{\sqrt{2\pi\kappa\hbar}} \int e^{ipy/\kappa\hbar} \Psi^*(q + \frac{y}{2}, t) \Psi(q - \frac{y}{2}, t) dy, \tag{6}$$

where the parameter κ was introduced, $\kappa \rightarrow 0$ corresponding to the classical limit when the coordinate and momentum operators must commute. Note that the last condition is different from the condition $\hbar \rightarrow 0$ because \hbar is also present as a multiplier of the time derivative in the Schrödinger equation. Thus, the limit $\hbar \rightarrow 0$ means more than the criterion for the commutativity of the position and momentum operators in the classical limit, and differs from the limit $\kappa \rightarrow 0$, which ensures the commutativity of these operators [18].

Let $y = \kappa\hbar\lambda_p$. The above equation can be re-written in terms of λ_p

$$W(q, p) = \sqrt{\frac{\kappa\hbar}{2\pi}} \int e^{ip\lambda_p} \Psi^*(q + \frac{\kappa\hbar\lambda_p}{2}, t) \Psi(q - \frac{\kappa\hbar\lambda_p}{2}, t) d\lambda_p. \tag{7}$$

Using the following change of variables,

$$u = q - \frac{\kappa\hbar\lambda_p}{2}, \quad v = q + \frac{\kappa\hbar\lambda_p}{2}, \tag{8}$$

let us define $\rho(u, v, t) = \Psi^*(v)\Psi(u)$. Since $\Psi(q, t)$ satisfies the time-dependent Schrödinger equation, it can be easily checked that $\rho(u, v, t)$ satisfies the following equation

$$i\kappa\hbar \frac{\partial}{\partial t} \rho(u, v, t) = [\hat{H}_u - \hat{H}_v] \rho(u, v, t), \tag{9}$$

where the Hamiltonians are $\hat{H}_u = \frac{(\hbar\kappa)^2}{2m} \frac{\partial^2}{\partial u^2} + V(u)$ and analogously for \hat{H}_v . Interestingly, equation (9) is reminiscent of the chiral decomposition method, in which the phase space variables are chosen in such a way that the Hamiltonian of the system decomposes into the difference of the Hamiltonians of two uncoupled systems [3,4,94].

To represent Eq. (9) in the representation-independent operator form, we introduce generalized Bopp pseudo-differential operators [28,51]

$$\begin{aligned} \hat{u} &= \hat{q} - \frac{\kappa \hbar \hat{\lambda}_p}{2}, & \hat{v} &= \hat{q} + \frac{\kappa \hbar \hat{\lambda}_p}{2}, \\ \hat{p}_u &= \hat{p} + \frac{\kappa \hbar \hat{\lambda}_x}{2}, & \hat{p}_v &= \hat{p} - \frac{\kappa \hbar \hat{\lambda}_x}{2}, \end{aligned} \tag{10}$$

and assume the following commutation relations

$$[\hat{u}, \hat{p}_u] = i\kappa \hbar, \quad [\hat{v}, \hat{p}_v] = -i\kappa \hbar. \tag{11}$$

In the $\kappa \rightarrow 0$ limit, Eq. (11) and Eq. (10) suggest that $[\hat{q}, \hat{p}] = 0$. We assume that this commutativity holds even for nonzero κ so that \hat{q} and \hat{p} can be considered as classical position and momentum operators.

Eq. (11) will be ensured if, in addition to $[\hat{q}, \hat{p}] = 0$, the following set of commutation relations holds:

$$[\hat{q}, \hat{\lambda}_x] = i, \quad [\hat{p}, \hat{\lambda}_p] = i, \quad [\hat{\lambda}_p, \hat{\lambda}_x] = 0. \tag{12}$$

Further we make the identification

$$\hat{\lambda}_x = \frac{\hat{p}}{\hbar}, \quad \hat{\lambda}_p = -\frac{\hat{Q}}{\hbar}, \tag{13}$$

and obtain the commutation relations with canonical pairs (\hat{q}, \hat{P}) and (\hat{Q}, \hat{p}) :

$$\begin{aligned} [\hat{Q}, \hat{p}] &= i\hbar, \quad [\hat{Q}, \hat{P}] = 0, \quad [\hat{p}, \hat{P}] = 0, \\ [\hat{q}, \hat{Q}] &= 0, \quad [\hat{q}, \hat{p}] = 0, \quad [\hat{q}, \hat{P}] = i\hbar. \end{aligned} \tag{14}$$

The Hamiltonian $\mathcal{H}_{qc} = \hat{H}_u - \hat{H}_v$ can be expressed in terms on operators $\hat{Q}, \hat{P}, \hat{q}$ and \hat{p} , as follows [18]:

$$\begin{aligned} \hat{\mathcal{H}}_{qc} &= \hat{H}_u - \hat{H}_v = \left[\frac{\hat{p}_u^2}{2m} + V(\hat{u}) \right] - \left[\frac{\hat{p}_v^2}{2m} + V(\hat{v}) \right] \\ &= \frac{\kappa \hat{p} \hat{P}}{m} + V\left(\hat{q} + \frac{\kappa \hat{Q}}{2}\right) - V\left(\hat{q} - \frac{\kappa \hat{Q}}{2}\right). \end{aligned} \tag{15}$$

As a result, in the (q, Q) representation (when \hat{q} and \hat{Q} operators are diagonal), equation (9) can be written as

$$i\hbar \frac{\partial}{\partial t} \Psi = \left[\frac{\hat{p} \hat{P}}{m} + \frac{1}{\kappa} V\left(q + \frac{\kappa Q}{2}\right) - \frac{1}{\kappa} V\left(q - \frac{\kappa Q}{2}\right) \right] \Psi, \tag{16}$$

where $\Psi(q, Q, t)$ is proportional to $\rho(u, v, t)$ [18].

In the limit $\kappa \rightarrow 0$, we get

$$i\hbar \frac{\partial}{\partial t} \psi_{KvN} = \left[\frac{\hat{p} \hat{P}}{m} + \frac{\partial V(q)}{\partial q} Q \right] \psi_{KvN} = \hat{\mathcal{H}}_c \psi_{KvN}, \tag{17}$$

where $\hat{\mathcal{H}}_{qc}^{\kappa \rightarrow 0} = \hat{\mathcal{H}}_c$ and $\psi_{KvN} = \Psi(q, Q, t)$. The above equation is KvN equation in the (q, Q) representation, where it is more quantum-like [80,87].

The Hamiltonian $\hat{\mathcal{H}}_c$ can be further re-written in terms of classical Hamiltonian H and the KvN equation takes the following form

$$i\hbar \frac{\partial}{\partial t} \psi = \hat{\mathcal{H}}_c \psi = \left(\frac{\partial \hat{H}}{\partial q} \hat{Q} + \frac{\partial \hat{H}}{\partial p} \hat{P} \right) \psi. \tag{18}$$

Note that we have removed the subscript KvN from the wave function, and therefore ψ should be understood as the KvN wave function in what follows.

In the representation (q, p) , according to commutation relations (14), \hat{P} and \hat{Q} are the following operators

$$\hat{P} = -i\hbar \frac{\partial}{\partial q}, \quad \hat{Q} = i\hbar \frac{\partial}{\partial p}, \tag{19}$$

and we obtain the Liouville equation (4) in the Schrödinger-like form.

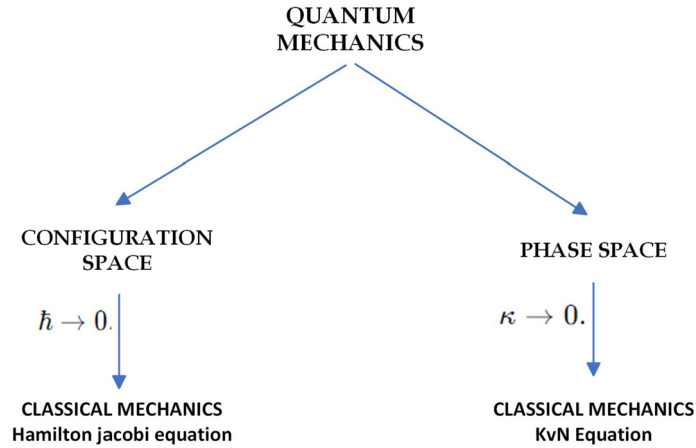


Fig. 1. Emergence of KvN mechanics.

Therefore, the KvN formalism for the classical theory can be motivated by the quantum mechanical phase space formalism based on the Wigner quasi-probability distribution function in the $\kappa \rightarrow 0$ limit. See [78] for an alternative hydrodynamic motivation of the Madelung type, and [71] for an algebraic approach to KvN mechanics. We summarize the ideas presented in this section using Fig. 1.

2.3. Relationship between Newtonian mechanics and KvN mechanics

A description of classical mechanics in various forms is outlined in the previous subsections. It is well known that Lagrange’s equation of motion, as well as Hamilton’s equation of motion lead to Newton’s equation of motion. In this subsection, we will see how one can arrive at the classical Hamiltonian equation of motion starting from the KvN mechanics in the Heisenberg picture [27]. In the Heisenberg picture, the operators evolve as

$$\hat{A}(t) = e^{i\hat{L}t} \hat{A}(0) e^{-i\hat{L}t} \tag{20}$$

leading to the following equation of motion

$$\frac{d\hat{A}(t)}{dt} = i[\hat{L}, \hat{A}(t)]. \tag{21}$$

Assuming (q, p) representation, for diagonal (multiplicative) position and momentum operators we get

$$\frac{dq}{dt} = i[\hat{L}, \hat{q}] = \frac{\partial H(q, p, t)}{\partial p}, \quad \frac{dp}{dt} = i[\hat{L}, \hat{p}] = -\frac{\partial H(q, p, t)}{\partial q}, \tag{22}$$

which are the Hamiltonian equation of motion in classical mechanics.

Another way to see that the KvN mechanics for definite initial values of q and p leads to Newtonian trajectories is the method of characteristics [91]. The KvN equation (17) is a linear partial differential equation $\psi_t + \frac{p}{m} \psi_q - \frac{\partial V}{\partial q} \psi_p = 0$, whose characteristic curves are given in parametric form by a system of ordinary differential equations

$$\frac{dt}{d\tau} = 1, \quad \frac{dq}{d\tau} = \frac{p}{m}, \quad \frac{dp}{d\tau} = -\frac{\partial V}{\partial q}. \tag{23}$$

The solution of (23) with initial values $q(t_0) = q_0$ and $p(t_0) = p_0$ are clearly a Newtonian trajectory $q(q_0, p_0, t) = q_N(t)$, $p(q_0, p_0, t) = m \frac{dq_N}{dt}$. The wave function ψ remains constant along characteristic curves. Therefore, if initially it is a delta-function localized around the initial values (q_0, p_0) , it will remain a delta-function localized around the Newtonian trajectory $(q_N(t), p_N(t))$ at every instant of time t .

3. Eisenhart-lift and KvN mechanics

3.1. Eisenhart-lift: brief introduction

Minkowski’s four-dimensional (4D) representation of special relativity was an important step towards the geometrization of the theory, which further deepened our understanding of special relativity and played a crucial role in the creation of general relativity. A similar approach to classical mechanics [49] and Newtonian theory of gravity led to the Newton-Cartan

(NC) theory [26,49]. The geometrization of any theory introduces a mathematical structure with appropriate properties and symmetries. For example, in the case of special relativity, the geometrization procedure introduces the Minkowski structure (\mathcal{M}, g) , where \mathcal{M} is the space-time manifold and g is the Lorentzian metric associated with it. The symmetry group of this space-time is the Poincaré group $ISO(3, 1)$. Similarly, NC theory introduces the Galilean structure (\mathcal{M}, h, τ) , where \mathcal{M} is a space-time manifold with a degenerate metric h and a nowhere vanishing 1-form τ . For a free particle (in 3D), the symmetry group is the Galilean group $Gal(3, 1)$.

The Newton-Cartan theory, a fascinating approach to the geometrization of Newtonian gravity, is not a simple geometric theory because it has a more complex structure than Lorentzian space-time due to the presence of a degenerate metric structure: a separate metric for space, a separate metric for time, which do not merge into one actual space-time metric. In order to have a deeper understanding of the NC theory, further research led to a geometric formulation of Newtonian gravity based on gauging the Bargmann algebra (centrally extended Galilean algebra) and to a possible role of Newton-Cartan theory in non-relativistic applications of the AdS/CFT correspondence [8].

Motivated by the problem of transforming the quantization of classical systems into a rigorous mathematical procedure, Alexander Kirillov, Bertram Kostant and Jean-Marie Souriau independently initiated a geometric quantization program in the 1960s [56,57,61,84,85]. Forming a bridge between quantum mechanics and the representation theory of Lie groups, geometric quantization provides a differential-geometric method for constructing a quantum theory corresponding to a classical system [82]. For examples of interesting interplay between geometric quantization and KvN mechanics, see, for example, [1,20,59].

A by-product of such research was the formulation of classical mechanics in terms of Bargmann structures [32,62]. In fact, such a geometric embedding of the classical dynamics was already established by Eisenhart [37]. However, surprisingly, at that time this publication did not attract much attention from physicists [40].

The simplest way to explain Eisenhart lift is to use Hamiltonian approach [21,44]. Given a classical dynamical system with Hamiltonian

$$H = \frac{1}{2m} \sum_{i,j=1}^n h^{ij}(q) p_i p_j + V(q, t), \tag{24}$$

the first step is to promote time t to a dynamical variable (enlarge the configuration space from $\{q_i\}$ to $\{q_i, t\}$). Since

$$\int_{t_i}^{t_f} L\left(q, \frac{dq}{dt}, t\right) dt = \int_{\sigma_i}^{\sigma_f} L\left(q, \frac{\dot{q}}{\dot{t}}, t\right) \dot{t} d\sigma,$$

where $\dot{q}_i = \frac{dq_i}{d\sigma}$, $\dot{t} = \frac{dt}{d\sigma}$, the new Lagrangian takes the form (h_{ij} matrix is inverse of h^{ij})

$$\tilde{L}(q, t, \dot{q}, \dot{t}) = \left[\frac{m}{2} \sum_{i,j=1}^n h_{ij}(q) \dot{q}^i \dot{q}^j \dot{t}^{-2} - V(q, t) \right] \dot{t}$$

and the momentum variable canonically conjugate to time is

$$p_t = \frac{\partial \tilde{L}}{\partial \dot{t}} = - \left[\frac{m}{2} \sum_{i,j=1}^n h_{ij}(q) \dot{q}^i \dot{q}^j \dot{t}^{-2} + V(q, t) \right] = -H.$$

Therefore, in order to turn time into a dynamical variable, we must impose a constraint

$$p_t + H(q, p, t) = 0, \tag{25}$$

which ensures reparametrization invariance with respect to the auxiliary parameter σ with the dimension of time [9,15].

Using $\dot{q}^i = \frac{\dot{t}}{m} \sum_{j=1}^n h^{ij} p_j$, we find $\sum_{i=1}^n \dot{q}^i p_i - \tilde{L} = \dot{t} H(q, p, t)$. Therefore the new Hamiltonian is

$$\tilde{H} = \sum_{i=1}^n \dot{q}^i p_i + \dot{t} p_t - \tilde{L} = \dot{t} [p_t + H(q, p, t)].$$

Because of the reparametrization invariance, \dot{t} remains arbitrary. Therefore, we can take $\dot{t} = 1$ and end up with the Hamiltonian

$$\tilde{H} = p_t + H(q, p, t) = p_t + \frac{1}{2m} \sum_{i,j=1}^n h^{ij} p_i p_j + V(q, t). \tag{26}$$

Of course, this Hamiltonian vanishes due to the constraint (25), a situation analogous to the invariance under general coordinate transformations in general relativity [9].

The main idea behind the Eisenhart lift is to introduce a new momentum p_s conjugate to a dummy configuration space variable s to make the Hamiltonian homogeneous in canonical momenta and turn it into a geodesic Hamiltonian (homogeneous quadratic function of momenta) [21,44]. So we replace the Hamiltonian (26) with the homogenized version (in the following, we use natural units with $\hbar = 1$, $c = 1$, and assume that s has the dimension of time, so p_s has the dimension of energy)

$$\mathcal{H} = \frac{1}{2m} \sum_{i,j=1}^n h^{ij}(q) p_i p_j + \frac{1}{m^2} p_s^2 V(q, t) + \frac{1}{m} p_s p_t. \tag{27}$$

Note that other conventions are also used in the literature: if p_s is assumed to have the dimension of mass, then s has the dimension of action per mass [35], and if p_s is assumed to be dimensionless, then s has the dimension of action [21].

Since s is a cyclic coordinate, p_s is conserved and we can take $p_s = m$. In this case, (27) reduces to (26). Thus, in fact, we have homogenized the constraint (25) to obtain a constraint that is quadratic in momenta [15]:

$$\mathcal{H} = \frac{1}{2m} \sum_{A,B=1}^{n+2} g^{AB} p_A p_B = 0, \tag{28}$$

where $p_{n+1} = p_t$, $p_{n+2} = p_s$ and the nonzero components of the inverse metric are $g^{ij} = h^{ij}$, $g^{n+1,n+2} = g^{n+2,n+1} = 1$, $g^{n+2,n+2} = 2V(q, t)/m$.

Since

$$\begin{pmatrix} 0 & 1 \\ 1 & 2\frac{V(q,t)}{m} \end{pmatrix}^{-1} = \begin{pmatrix} -2\frac{V(q,t)}{m} & 1 \\ 1 & 0 \end{pmatrix},$$

the constraint (28) can be interpreted as a mass-shell condition for a massless particle in space-time with a Brinkmann-type metric

$$dS^2 = \sum_{i,j=1}^n h_{ij} dq^i dq^j + 2ds dt - 2\frac{V(q, t)}{m} dt^2. \tag{29}$$

Newtonian trajectories in the subspace (q_i, t) (space-time) are projections of zero geodesics in the Bargmann space (q_i, t, s) with the Eisenhart metric (29) [35,95].

There is some arbitrariness in generalizing the null constraint (25) to (28). In particular, we can multiply (28) by $\Omega^{-1}(q, t)$, where the conformal factor $\Omega(q, t)$ nowhere vanishes. In this case, instead of the Eisenhart metric (29), we get the metric

$$dS^2 = \Omega(q, t) \left[\sum_{i,j=1}^n h_{ij} dq^i dq^j + 2ds dt - 2\frac{V(q, t)}{m} dt^2 \right]. \tag{30}$$

The metric in this form was first introduced by Lichnerowicz [15].

3.2. Eisenhart-lift in KvN mechanics: examples

3.2.1. Eisenhart lift of KvN oscillator

The study of harmonic oscillators has always been a good starting point for a deeper understanding of the physics of our world. As Sidney Coleman once said: “The career of a young theoretical physicist consists of treating the harmonic oscillator in ever-increasing levels of abstraction” [72]. Therefore, we will also use the KvN harmonic oscillator to get a crude idea of the Eisenhart lift in KvN mechanics.

The equation of motion of the KvN harmonic oscillator in the (q, Q) -representation and assuming that the mass and spring constant are equal to unity is as follows:

$$i\hbar \frac{\partial}{\partial t} \psi(q, Q, t) = (\hat{p} \hat{P} + qQ) \psi(q, Q, t). \tag{31}$$

Using the following transformation

$$\begin{aligned} q &= \frac{u + v}{2}, & Q &= u - v, \\ \hat{p} &= \frac{\hat{p}_u + \hat{p}_v}{2}, & \hat{P} &= \hat{p}_u - \hat{p}_v, \end{aligned} \tag{32}$$

the KvN equation of motion for harmonic oscillator becomes

$$i\hbar \frac{\partial}{\partial t} \psi(u, v, t) = (\hat{H}_u - \hat{H}_v) \psi(u, v, t), \tag{33}$$

where $\hat{H}_w = \frac{1}{2} (\hat{p}_w^2 + w^2)$ with $w = u, v$.

If the Hamiltonian in the equation (31) is considered as the Hamiltonian of a classical system with configuration space variables q and Q , the corresponding Eisenhart-lift metric is given by

$$dS_{HO}^2 = 2dq dQ + 2dtds - 2Qq dt^2, \tag{34}$$

and similar reasoning for the Hamiltonian in equation (33) leads to

$$dS_{HO}^2 = du^2 - dv^2 + 2dtds - (u^2 - v^2) dt^2. \tag{35}$$

Both Eisenhart-metric expressions (34) and (35) are equivalent and related by the transformation $q = \frac{u+v}{2}$, $Q = u - v$.

Since the determinant of the matrix

$$\begin{pmatrix} -(u^2 - v^2) & 1 \\ 1 & 0 \end{pmatrix}$$

is -1 , this matrix has one negative and one positive eigenvalue. Then from (35) it is clear that this metric is an ultrahyperbolic metric, in contrast to the Eisenhart lift of ordinary classical dynamics, which gives a Lorentzian metric.

3.2.2. Eisenhart lift of linear potential in KvN mechanics

It follows from (17) that the equation of motion for the linear potential $V(q) = gq$ (assuming unit mass) in KvN mechanics in the (q, Q) -representation has the form

$$i\hbar \frac{\partial}{\partial t} \psi(q, Q, t) = (\hat{p}\hat{P} + g\hat{Q})\psi(q, Q, t). \tag{36}$$

After using the same transformation equation (32), the KvN equation of motion (36) becomes

$$i\hbar \frac{\partial}{\partial t} \psi(u, v, t) = (\hat{H}_u - \hat{H}_v)\psi(u, v, t) \tag{37}$$

Where, $\hat{H}_w = \frac{\hat{p}_w^2}{2} + gw$ and $w = u, v$. As in the case of harmonic oscillator, equations (36) and (37) suggest two equivalent forms for the corresponding Eisenhart metric

$$\begin{aligned} dS_{Linear}^2 &= 2dq dQ + 2dtds - 2gQ dt^2, \\ dS_{Linear}^2 &= du^2 - dv^2 + 2dt ds - 2g(u - v)dt^2. \end{aligned} \tag{38}$$

Again, these different forms of the same Eisenhart metric are related by the transformation $q = \frac{u+v}{2}$, $Q = u - v$, and the second form suggests that the metric is of the ultrahyperbolic signature.

3.3. Eisenhart-lift of general KvN dynamical system

The simplest way to geometrize the KvN mechanics is to begin from the KvN Hamiltonian that follows from (17) and consider it as describing classical (not KvN) system:

$$H = \frac{pP}{m} + \frac{\partial V}{\partial q} Q. \tag{39}$$

Homogenizing this Hamiltonian as described above, we get

$$\mathcal{H} = \frac{pP}{m} + \frac{\partial V}{\partial q} Q \frac{p_s^2}{m^2} + \frac{1}{m} p_s p_t, \tag{40}$$

which corresponds to the inverse metric

$$g^{qQ} = g^{Qq} = 1, \quad g^{st} = g^{ts} = 1, \quad g^{ss} = \frac{2}{m} \frac{\partial V}{\partial q} Q, \tag{41}$$

all other components being zero. Inverting g^{AB} to calculate the metric tensor g_{AB} , we get the corresponding Eisenhart metric

$$dS^2 = 2dq dQ + 2dt ds - \frac{2Q}{m} \frac{\partial V(q)}{\partial q} dt^2. \tag{42}$$

Harmonic oscillator and linear potential examples considered above are just special cases of (42).

However, for (42) to be considered as the Eisenhart lift of the KvN dynamical system, we have to demonstrate something more: that the KvN equation (17) can be seen as null-reduction (reduction in the s -direction) of the massless Klein-Gordon equation in the Bargmann space with the Eisenhart metric (42).

The massless Klein-Gordon equation in general metric is given by

$$\square\chi = \frac{1}{\sqrt{|g|}}\partial_\mu\left(\sqrt{|g|}g^{\mu\nu}\partial_\nu\chi\right) = 0. \tag{43}$$

Using the metric in (42), we get the explicit form of curved KG for the massless scalar field $\chi(t, s, q, Q)$ as follows

$$\frac{\partial^2\chi}{\partial q\partial Q} + \frac{Q}{m}\frac{\partial V}{\partial q}\frac{\partial^2\chi}{\partial s^2} + \frac{\partial^2\chi}{\partial t\partial s} = 0, \tag{44}$$

which after the field redefinition

$$\chi(t, s, q, Q) = e^{ims}\psi_{KvN}(t, q, Q), \tag{45}$$

reduces to the equation of the form

$$i\frac{\partial\psi_{KvN}}{\partial t} = \left(Q\frac{\partial V}{\partial q} - \frac{1}{m}\frac{\partial^2}{\partial q\partial Q}\right)\psi_{KvN}, \tag{46}$$

which is the KvN equation in the (q, Q) -representation for the classical Hamiltonian $H = \frac{p^2}{2m} + V(q)$, (17) being its operator version.

Thus, the KvN equation can be considered as a null-reduction (reduction in the s -direction) of the Klein-Gordon equation in the Eisenhart metric background, much like the quantum mechanical case [15,32,53]. Therefore, (42) is indeed the Eisenhart lift of the general one-dimensional KvN system. Generalization to multidimensional KvN systems does not cause difficulties.

An interesting difference from the usual quantum mechanics is that in the KvN-Case the Eisenhart metric is of signature $(-, -, +, +)$. This implies that the free KvN-system gives rise to $SO(2, 2)$ symmetric Eisenhart metric, while the free Schrödinger-system gives rise to $SO(1, 2)$ symmetric Eisenhart metric (for one-dimensional configuration space). Thus, group-theoretic analyzes like those in [69] or [35] deserve further study.

3.4. Some applications

An immediate application of the Eisenhart lift of KvN mechanics is to obtain relations between KvN systems with a harmonic potential, a linear potential, and a free particle. The quantum mechanical analog [30] hints that for this to be possible, the Eisenhart metric must be conformally flat.

In $n > 3$ dimensions, conformal flatness is guaranteed by the vanishing of the Weyl tensor

$$W_{\mu\nu\gamma\delta} = R_{\mu\nu\gamma\delta} - \frac{1}{n-2}\left(g_{\mu\gamma}R_{\nu\delta} - g_{\nu\gamma}R_{\mu\delta} - g_{\mu\delta}R_{\nu\gamma} + g_{\nu\delta}R_{\mu\gamma}\right) + \frac{1}{(n-1)(n-2)}\left(g_{\mu\gamma}g_{\nu\delta} - g_{\nu\gamma}g_{\mu\delta}\right)R, \tag{47}$$

where $R_{\mu\nu\gamma\delta}$, $R_{\mu\nu}$, and R are the Riemannian curvature tensor, the Ricci tensor, and the scalar curvature for the metric $g_{\mu\nu}$, respectively. For a general KvN mechanical system, using the lifted metric (42) in the Weyl tensor (47), we can calculate the non-zero components of the Weyl tensor as follows:

$$W_{qtqt} = W_{tqtq} = -W_{qtqq} = -W_{tqqt} = \frac{Q}{m}\frac{\partial^3 V(q, t)}{\partial q^3}. \tag{48}$$

From the conformal flatness condition $W_{\mu\nu\gamma\delta} = 0$ we obtain:

$$V(q, t) = \frac{1}{2}C_1(t)q^2 + C_2(t)q + C_3(t), \tag{49}$$

where C_1, C_2 and C_3 are the integration constants.

Hence we obtain a class of potentials for which the KvN Eisenhart metric (42) is conformally flat. The result is the same as for the Lorentzian Eisenhart lift [30,34]: only up to quadratic-in-the-position potentials is the corresponding Eisenhart metric conformally flat.

3.4.1. Equivalence of a harmonic oscillator to a free particle

For the classical harmonic potential $V(q) = \frac{1}{2}q^2$, the corresponding Eisenhart metric takes the following form (we have added the Lichnerowicz conformal factor)

$$dS_{HO}^2 = \Omega(t)(2dq dQ + 2dt ds - 2Q qdt^2). \tag{50}$$

Using the transformation $q = \frac{v+u}{2}$, $Q = u - v$, the metric is transformed into

$$dS_{HO}^2 = \Omega(t) \left(du^2 - dv^2 + 2dt ds - (u^2 - v^2)dt^2 \right). \tag{51}$$

We know that this Eisenhart-Lichnerowicz metric is conformally equivalent to the Eisenhart metric for a free KvN particle

$$dS_{Free}^2 = d\eta^2 - d\xi^2 + 2d\tau d\zeta. \tag{52}$$

Thus there exist a coordinate transformation $(u, v, s, t) \rightarrow (\eta, \xi, \zeta, \tau)$ between (51) and (52). Since calculations almost exactly mirror the quantum case considered in [30], we present only the final results. We choose the conformal factor $\Omega(t) = \sec^2(t)$ and take the general coordinate transformation as $u = \Phi(\eta, \xi, \tau)$, $v = R(\eta, \xi, \tau)$, $s = \zeta + \Theta(\eta, \xi, \tau)$, $t = T(\eta, \xi, \tau)$. The explicit form of the transformation (with all integration constants set to zero) is

$$\begin{aligned} t &= \tan^{-1}(\tau), \quad u = \frac{-\eta}{\sqrt{\tau^2 + 1}}, \quad v = \frac{-\xi}{\sqrt{\tau^2 + 1}}, \\ s &= \zeta + \frac{1}{2(\tau^2 + 1)} \left[(\eta^2 - \xi^2) \tau \right]. \end{aligned} \tag{53}$$

This transformation between Eisenhart metrics for KvN Harmonic oscillator and KvN free particle induce a transformation between the corresponding KvN wave functions $\psi_{HO}(u, v, t, s)$ and $\psi_{free}(\eta, \xi, \tau, \zeta)$ in the equation (46):

$$\psi_{HO} = \sqrt{1 + \tau^2} \exp \left[\frac{im [(\xi^2 - \eta^2) \tau]}{2(\tau^2 + 1)} \right] \psi_{free}. \tag{54}$$

One remark is pertinent here. When the metric (42) is multiplied by Lichnerowicz conformal factor $\Omega(t)$ and used in (43), instead of (44) we obtain

$$\frac{\partial^2 \chi}{\partial q \partial Q} + \frac{Q}{m} \frac{\partial V}{\partial q} \frac{\partial^2 \chi}{\partial s^2} + \frac{\partial^2 \chi}{\partial t \partial s} + \frac{1}{2\Omega} \frac{\partial \Omega}{\partial t} \frac{\partial \chi}{\partial s} = 0, \tag{55}$$

and to get the KvN equation (46) we need to replace (45) by

$$\chi(t, s, q, Q) = \Omega^{-1/2} e^{ims} \psi_{KvN}(t, q, Q). \tag{56}$$

This explains the $\sqrt{1 + \tau^2}$ prefactor before the exponent in (54). Because of this time-dependent prefactor, the transformation (54) is not unitary, and the corresponding mapping of a harmonic oscillator into a free particle cannot be considered as an equivalence principle, in contrast to the case of a linear potential (see below). This situation is completely analogous to the quantum case [30]. Note, however, that there is a broader “conformal” context in which the correspondence of a harmonic oscillator to a free particle fits [42,93].

The connection between quantum isotropic oscillators with a time-independent frequency and a free particle is usually attributed to Niederer [73]. However, apparently, for the first time such a connection was noticed in the field of optics [86,92] and explicitly or implicitly rediscovered by many authors [48,54,83]. This relationship has recently been discussed in the context of KvN mechanics [68], and extended to anisotropic oscillators with time-dependent frequency [93].

3.4.2. Equivalence of a linear potential to a free particle

A similar analysis can also be carried out for a linear potential. The Eisenhart metric for the KvN linear potential $V = gq$ (assuming unit mass) has the form (38). It is converted to the free metric (52) by the following transformation (integration constants are again set to zero)

$$t = \tau, \quad u = \eta - \frac{1}{2}g\tau^2, \quad v = \xi - \frac{1}{2}g\tau^2, \quad s = \zeta + (\eta - \xi)g\tau. \tag{57}$$

The corresponding transformation of the KvN wave function

$$\psi_{Linear} = \exp[i(\xi - \eta)g\tau] \psi_{free}, \tag{58}$$

is unitary and represents Einstein’s principle of equivalence in KvN mechanics.

The relation (58) in (q, Q) coordinates reads

$$\psi_{Linear}(q, Q, t) = e^{-iQg\tau} \psi_{free} \left(q + \frac{1}{2}gt^2, Q, t \right), \quad (59)$$

which is the result obtained in [78] with a different method.

4. Conclusions

KvN mechanics, a Hilbert space interpretation of classical mechanics, naturally appears as a limiting situation of the Wigner function formalism [19]. Eisenhart lift of the KvN Hamiltonian opens the way to a geometric understanding of the KvN mechanics, since the massless Klein-Gordon equation in curved space for the metric (42) at null-reduction gives exactly the KvN equation. Using this geometric picture, we found the transformations of coordinates, as well as KvN wave functions, that relate KvN harmonic oscillator or the linear potential to a KvN free particle. In the case of linear potential, we recover Einstein's equivalence principle in KvN mechanics first obtained in [78].

Eisenhart lift of KvN mechanics is very similar to the similar lift of quantum mechanics [15,32,53]. This is not surprising, since the KvN system (17) can be interpreted as a kind of quantum system with a Hamiltonian linearly dependent on the classically "hidden" variables Q and P , as a result of which the classical dynamics is induced in the subspace (q, p) .

An interesting difference from the quantum case is that the Eisenhart metric in the KvN case has an ultrahyperbolic rather than a Lorentzian signature. This is because the kinetic energy in the KvN Hamiltonian, since it must be linear in "hidden" momenta, is pseudo-Euclidean rather than positive definite Euclidean. Such an unusual kinetic energy in the context of classical mechanics was first considered in 1935 by Drach in search of potentials that admit a cubic integral of motion with respect to momenta [31]. References [22,39,41] consider the Eisenhart lift of such classical systems and show that a metric with an ultrahyperbolic signature arises.

Metrics with the ultrahyperbolic signature $(-, -, +, +)$ are special cases of the so-called Kleinian space-times with the complete symmetry between space and time, which are relatively unknown to physicists [13], maybe because it is widely believed that ultrahyperbolic space-times are not deterministic in a physically meaningful sense [88]. Nevertheless, such space-times, in addition to the Eisenhart lift of the Drach-type classical mechanical and KvN systems, arise in a number of different physical contexts, see for example [5,13,14,29,38,43,76,81].

Declaration of competing interest

The authors declare that they have no known competing financial interests or personal relationships that could have appeared to influence the work reported in this paper.

Data availability

No data was used for the research described in the article.

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